

The TauP Toolkit:
Flexible Seismic Travel-Time and Raypath Utilities
Version 2.7
Documentation

H. Philip Crotwell, Thomas J. Owens
School of Earth, Ocean and Environment
University of South Carolina
<http://www.seis.sc.edu>
crotwell@seis.sc.edu

Contents

1	Overview	1
2	Distribution	2
2.1	What and Where	2
2.2	Advantages of the Current Release	2
2.3	Future Plans	3
3	Tools	4
3.1	Default Parameters	4
3.2	TauP_Time	6
3.3	TauP_Pierce	7
3.4	TauP_Path	9
3.5	TauP_Wavefront	10
3.6	TauP_GUI	11
3.7	TauP_Curve	12
3.8	TauP_SetSac	13
3.9	TauP_Table	14
3.10	TauP_PhaseDescribe	15
3.11	TauP_VelocityMerge	16
3.12	TauP_VelocityPlot	17
3.13	TauP_SlownessPlot	17
3.14	TauP_Create	18
4	Phase naming in TauP	19
5	Creating and Saving Velocity Models	22
5.1	Velocity Model Files	22
5.2	Using Saved Tau Models	23
6	Programming Interface	25
6.1	Java	25
6.2	Scripting	26
6.2.1	Groovy	26

6.2.2	Jacl	27
6.3	C	29
7	Examples	32
7.1	Velocity Model Files	32
7.2	Creating the Model	32
7.3	Travel Times	33
7.4	Pierce Points	34
7.5	Path	35
7.6	Travel Time Curves	35
A	Installing	37
A.0.1	Max OSX Install	37
A.0.2	Snap Install	37
A.0.3	Manual Install	37
B	Troubleshooting	39

Disclaimer and License

The TauP Toolkit: Flexible Seismic Travel-Time and Raypath Utilities.
Copyright (C) 1998-2022 University of South Carolina

This program is free software; you can redistribute it and/or modify it under the terms of the GNU LESSER GENERAL PUBLIC LICENSE as published by the Free Software Foundation; either version 3 of the License, or (at your option) any later version.

This program is distributed in the hope that it will be useful, but WITHOUT ANY WARRANTY; without even the implied warranty of MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE. See the GNU LESSER GENERAL PUBLIC LICENSE for more details.

You should have received a copy of the GNU LESSER GENERAL PUBLIC LICENSE along with this program. If not, see <<http://www.gnu.org/licenses/>>.

The current version of The TauP Toolkit can be found at <http://www.seis.sc.edu>

Bug reports and comments should be directed to
H. Philip Crotwell or Tom Owens
at the TauP email list, taup@seis.sc.edu

The TauP Toolkit is available free under the terms of the GNU LESSER GENERAL PUBLIC LICENSE, found in the LICENSE file within the distribution. It gives you specific rights to use, modify and redistribute this software.

1 Overview

The algorithms employed within the TauP package are based on the method of (Buland and Chapman, 1983). The IASPEI *ttimes* package is a widely-used implementation of the methodology.

The main benefit of this new package is a marked increase in flexibility. It will handle many types of velocity models, instead of being limited to just a few. A new phase parser allows times to be computed for virtually any seismic phase. The use of Java enables this code to be run on a variety of machine and operating system types, without recompiling. This package also offers the extraction of derivative information, such as ray paths through the earth, pierce and turning points, as well as travel time curves.

A paper has been published in Seismological Research Letters, (Crotwell, Owens, and Ritsema, 1998), that is intended to be used as a companion to this manual. While this manual mainly focuses on the practicalities of using the codes, the paper is able to go into more detail on the methodology. A pdf copy of this paper is also available in the distribution.

2 Distribution

2.1 What and Where

The current distribution of the TauP package is 2.7, dated June XX, 2022.

The distribution directory obtained from either the gzipped tar file or the jar file contains:

README.md	getting started information
LICENSE	the GNU LGPL license
StdModels	standard models included in the jar in lib
bin	directory containing “wrapper scripts” to start the tools, each will print a usage with a <code>-help</code> command line argument.
lib	all the Java classes included in the package, along with saved models for prem, iasp91, and ak135 in the TauP jar file. Also included are dependency jars.
docs	a directory with the TauP paper published in SRL and this manual, installation instructions are in the appendix. Also included are javadocs, example properties, history, Maple version of equations used, and a simple model file.
groovy	a directory with Groovy example script for accessing the TauP package directly within scripts.
jacl	a directory with Jacl examples for accessing the TauP package directly within scripts.
native	a directory with a C library and example program that use the Java Native Interface, providing a basic interface between C programs and the TauP package.
src	a directory with all of the java source code.
gradlew	rebuild TauP using Gradle.
gradle	helper file for rebuild TauP using Gradle.

The `taup.jar` file contains everything needed for a working version of the package. This greatly simplifies the installation process and reduces potential errors. See appendix [A](#) for detailed installation instructions.

2.2 Advantages of the Current Release

The increased flexibility of this package provides significant advantages. Among these are:

1. The ability to use many different models. We include a variety of previously created models as well as the option of creating your own models. A conscious effort was made to make as few assumptions as possible about the nature of the model. Therefore, even models that have very different structures than common global models can be used.
2. Phase parsing. Phases are not hard coded into the program, instead the phase names are parsed. This creates an opportunity for the study of less common phases that are not present in previous travel time calculators.
3. Programming interface for Java. Because of the use of the Java programming language, all of the tools exist simultaneously as both applications and libraries. Thus, any Java code that has a need for travel times can load and manipulate the objects within this package. In addition, Groovy, a popular Java scripting language, provides a simple means of directly accessing the public methods within the package.

2.3 Future Plans

There are several ideas for improvements that we may pursue, such as:

1. A GUI. A graphical user interface would greatly improve the usefulness of this package, especially for non command line uses such as on the Macintosh or within web browsers. The beginnings of such a GUI are there in the TauP tool, but at present it cannot access all of the functionality of the tools.
2. Use of the τ function. In spite of the name, TauP does not yet use Tau splines. At present I do not believe that this would provide a large improvement over the current linear interpolation, but it is likely worth doing.
3. Web based applet. One of Java's main uses currently is for the development of web based applets. An applet is a small application that is downloaded and executed within a web browser. This is an attractive opportunity and we have a simple example of one included in this distribution. There are difficulties as the network time to download the model files may be unacceptable, as well as the lack of support for Java 1.1 in current browsers. A client server architecture as well as the continued improvement of commercial web browsers may be able to address these issues.
4. 1.1D models. There is nothing in the method that requires the source and receiver velocity models to be the same. With this idea, a separate crustal model appropriate to each region could be used for the source and receiver.
5. WKBJ synthetics. The calculation of τ is a necessary step for WKBJ synthetics, and so this is a natural direction. It likely involves significant effort, however.

3 Tools

Tools included with the TauP package:

<code>taup time</code>	calculates travel times.
<code>taup pierce</code>	calculates pierce points at model discontinuities and specified depths.
<code>taup path</code>	calculates ray paths, depth versus epicentral distance.
<code>taup wavefront</code>	calculates wavefronts in steps of time, depth versus epicentral distance.
<code>taup gui</code>	a GUI that incorporates the time, pierce and path tools.
<code>taup curve</code>	calculates travel time curves, time versus epicentral distance.
<code>taup table</code>	outputs travel times for a range of depths and distances in an ASCII file
<code>taup setsac</code>	puts theoretical arrival times into sac header variables.
<code>taup velplot</code>	output velocity model as a gmt script.
<code>taup slowplot</code>	output slowness model as a gmt script.
<code>taup phase</code>	textual description of the path the phase takes through the model.
<code>taup create</code>	creates a .taup model from a velocity model.

Each tool is a Java application and has an associated wrapper to make execution easier: sh scripts for UNIX and bat files for windows. The applications are machine independent but the wrappers are OS specific. For example, to invoke TauP_Time under UNIX, you could type

```
java -Dtaup.model.path=${TAUPPATH} edu.sc.seis.TauP.TauP_Time -mod prem
```

or simply use the script that does the same thing,

```
taup time -mod prem
```

Each tool has a `--help` flag that will print a usage summary, as well as a `--version` flag that will print the version.

TauP is moving towards a single application with subcommands, but we provide individual scripts for compatibility. These two commands produce the same result, but the first is preferred and the second style will be removed in version 3.0.

```
taup time -mod prem -deg 30 -ph P taup-time -mod prem -deg 30 -ph P
```

3.1 Default Parameters

Each of the tools use Java Properties to allow the user to specify values for various parameters. The properties all have default values, which are overridden by values from a Properties file. The tools use a text file to load the properties. It reads `.taup` in the current directory, which overwrites values read in from `.taup` in the user's home directory. Properties may also be specified by the `--prop` command line argument. In addition, many of the properties can be overridden by command line arguments.

The form of the properties file is very simple. Each property is set using the form

```
taup.property.name=value
```

one property per line. Comment lines are allowed, and begin with a #. Additionally, the names of all of the properties follow a convention of prepending “`taup.`” to the name of the property. This helps to avoid name collisions when new properties are added.

The currently used properties are:

taup.model.name the name of the initial model to be loaded, `iasp91` by default.

taup.model.path search path for models. There is no default, but the value in the `.taup` file will be concatenated with any value of `taup.model.path` from the system properties. For example, the environment variable `TAUPPATH` is put into the system property `taup.model.path` by the wrapper shell scripts.

taup.source.depth initial depth of the source, 0.0 km by default.

taup.phase.list initial phase list, combined with `taup.phase.file`. The defaults are `p, s, P, S, Pn, Sn, PcP, ScS, Pdiff, Sdiff, PKP, SKS, PKiKP, SKiKS, PKIKP, SKIKS`.

taup.phase.file initial phase list, combined with `taup.phase.list`. There is no default value, but the default value for `taup.phase.list` will not be used if there is a `taup.phase.file` property.

taup.depth.precision precision for depth output, the default is 1 decimal digit. Note that this is precision, not accuracy. Just because you get more digits doesn't imply that they have any meaning.

taup.distance.precision precision for distance output, the default is 2 decimal digits. Note that this is precision, not accuracy. Just because you get more digits doesn't imply that they have any meaning.

taup.latlon.precision precision for latitude and longitude output, the default is 2 decimal digits. Note that this is precision, not accuracy. Just because you get more digits doesn't imply that they have any meaning.

taup.time.precision precision for time, the default is 2 decimal digits. Note that this is precision, not accuracy. Just because you get more digits doesn't imply that they have any meaning.

taup.rayparam.precision precision for ray parameter, the default is 3 decimal digits. Note that this is precision, not accuracy. Just because you get more digits doesn't imply that they have any meaning.

taup.maxRefraction The maximum degrees that a `Pn` or `Sn` can refract along the moho. Note this is not the total distance, only the segment along the moho. The default is 20 degrees.

taup.maxDiffraction The maximum degrees that a `Pdiff` or `Sdiff` can diffract along the CMB. Note this is not the total distance, only the segment along the CMB. The default is 60 degrees.

taup.maxKmpsLaps The maximum number of laps around the earth for `kpms` style phases. Note this is the number of laps, not number of arrivals, so a value of 1 would give 2 arrivals, one going the short path and one the long way around. This can be fractional, so 0.5 would exclude the long way around path. The default is 1.

taup.path.maxPathInc maximum distance in degrees between points of a path. This does a simple linear interpolant between nearby values in order to make plots look better. There is no improvement in the accuracy of the path.

taup.table.locsat.maxdiff maximum distance in degrees for which `Pdiff` or `Sdiff` are put into a `locsat` table. Beyond this distance `Pdiff` and `Sdiff` will not be added to the table, even though they may show up in the output of `TauP_Time`. Instead, the next later arriving phase, if any, will be used instead. The default is 105 degrees.

taup.create.minDeltaP Minimum difference in slowness between successive slowness samples. This is used to decide when to stop adding new samples due to the distance check. Used by `TauP_Create` to create new models. The default is 0.1 sec/rad.

taup.create.maxDeltaP Maximum difference in slowness between successive slowness samples. This is used to split any layers that exceed this slowness gap. Used by TauP_Create to create new models. The default is 11.0 sec/rad.

taup.create.maxDepthInterval Maximum difference between successive depth samples. This is used immediately after reading in a velocity model, with layers being split as needed. Used by TauP_Create to create new models. The default is 115 km.

taup.create.maxRangeInterval Maximum difference between successive ranges, in degrees. If the difference in distance for two adjacent rays is greater than this, then a new slowness sample is inserted halfway between the two existing slowness samples. The default is 2.5 degrees.

taup.create.maxInterpError Maximum error for linear interpolation between successive sample in seconds. TauP_Create uses this to try to insure that the maximum error due to linear interpolation is less than this amount. Of course, this is only an approximation based upon an estimate of the curvature of the travel time curve for surface focus turning waves. In particular, the error for more complicated phases is greater. For instance, if the true error for P at 30 degrees is 0.03 seconds, then the error for PP at 60 degrees would be twice that, 0.06 seconds. Used by TauP_Create to create new models. The default is 0.05 seconds.

taup.create.allowInnerCoreS Should we allow J phases, S in the inner core? Used by TauP_Create to create new models. The default is true. Setting it to false slightly reduces storage and model load time.

Phase files, specified with the `taup.phase.file` property, are just text files with phase names, separated by either spaces, commas or newlines. In section 4 the details of the phase naming convention are introduced. By and large, it is compatible with traditional seismological naming conventions, with a few additions and exceptions. Also, for compatibility with *ttimes*, you may specify `ttp`, `ttp+`, `tts`, `tts+`, `ttbasic` or `ttall` to get a phase list corresponding to the *ttimes* options.

3.2 TauP_Time

TauP_Time takes either a `.taup` file generated by TauP_Create or a velocity model in `.nd` or `.tvel` format and generates travel times for specified phases through the given earth model.

The usage is:

```
piglet 1>bin/taup time --help
Usage: taup time [arguments]
    or, for purists, java edu.sc.seis.TauP.TauP_Time [arguments]
```

Arguments are:

```
-ph phase list      -- comma separated phase list
-pf phasefile      -- file containing phases

-mod[el] modelname -- use velocity model "modelname" for calculations
                    Default is iasp91.

-h depth           -- source depth in km

--stadepth depth   -- receiver depth in km
```

Distance is given by:

```

-deg degrees          -- distance in degrees,
-km kilometers        -- distance in kilometers,
                       assumes radius of earth is 6371km,

or by giving the station and event latitude and longitude,
                       assumes a spherical earth,

-sta[tion] lat lon -- sets the station latitude and longitude
-evt      lat lon -- sets the event latitude and longitude

--first              -- only output the first arrival for each phase, no triplcations
--rayp               -- only output the ray parameter
--time               -- only output travel time
--rel phasename      -- also output relative travel time

--json               -- output travel times as json

-o [stdout|outfile]  -- output is redirected to stdout or to the "outfile" file
--prop [propfile]    -- set configuration properties
--debug              -- enable debugging output
--verbose            -- enable verbose output
--version            -- print the version
--help               -- print this out, but you already know that!

```

The `modelname` is from `modelname.taup`, a previously created file from `TauP.Create` or a `modelname.nd` or `modelname.tvel` velocity model file. If there is insufficient information given on the command line, then you start in interactive mode, otherwise it assumes you only want one set of times.

The phases are specified on the command line with the `-ph` option, in a phase file with the `-pf` option, or in a properties file. The model, phases, depth and distance can be changed within the interactive section of `TauP.Time`.

For example: `taup time -mod prem -h 200 -ph S,P -deg 57.4`

gives you arrival times for S and P for a 200 kilometer deep source at a distance of 57.4 degrees.

```

piglet 2>taup time -mod prem -h 200 -ph S,P -deg 57.4

```

Model: prem

Distance (deg)	Depth (km)	Phase Name	Travel Time (s)	Ray Param p (s/deg)	Takeoff (deg)	Incident (deg)	Purist Distance	Purist Name
57.40	200.0	P	566.77	6.969	31.18	21.31	57.40	= P
57.40	200.0	S	1028.61	13.018	32.34	22.00	57.40	= S

3.3 TauP_Pierce

`TauP_Pierce` uses a model like `TauP.Time` but determines the angular distances from the epicenter at which the specified rays pierce discontinuities or specified depths in the model.

The usage is:

```
piglet 3>taup pierce --help
```

```
Usage: taup pierce [arguments]
```

```
or, for purists, java edu.sc.seis.TauP.TauP_Pierce [arguments]
```

Arguments are:

```
-ph phase list      -- comma separated phase list
```

```
-pf phasefile      -- file containing phases
```

```
-mod[el] modelname -- use velocity model "modelname" for calculations
                    Default is iasp91.
```

```
-h depth           -- source depth in km
```

```
--stadepth depth  -- receiver depth in km
```

Distance is given by:

```
-deg degrees      -- distance in degrees,
```

```
-km kilometers    -- distance in kilometers,
                    assumes radius of earth is 6371km,
```

or by giving the station and event latitude and longitude,
assumes a spherical earth,

```
-sta[tion] lat lon -- sets the station latitude and longitude
```

```
-evt          lat lon -- sets the event latitude and longitude
```

```
-az azimuth      -- sets the azimuth (event to station)
                    used to output lat and lon of pierce points
                    if the event lat lon and distance are also
                    given. Calculated if station and event
                    lat and lon are given.
```

```
-baz backazimuth -- sets the back azimuth (station to event)
                    used to output lat and lon of pierce points
                    if the station lat lon and distance are also
                    given. Calculated if station and event
                    lat and lon are given.
```

```
--first         -- only output the first arrival for each phase, no triplications
```

```
-rev            -- only prints underside and bottom turn points, e.g. ^ and v
```

```
-turn          -- only prints bottom turning points, e.g. v
```

```
-under         -- only prints underside reflection points, e.g. ^
```

```
-pierce depth   -- adds depth for calculating pierce points
```

```
-nodiscon      -- only prints pierce points for the depths added with -pierce
```

```
-o [stdout|outfile] -- output is redirected to stdout or to the "outfile" file
```

```
--prop [propfile] -- set configuration properties
```

```
--debug        -- enable debugging output
```

```
--verbose      -- enable verbose output
```

```
--version      -- print the version
--help        -- print this out, but you already know that!
```

The `-rev`, `-turn` and `-under` flags are useful for limiting the output to just those points you care about. The `-pierce` depth option allows you to specify a “pierce” depth that does not correspond to an actual discontinuity. For instance, where does a ray pierce 300 kilometers above the CMB?

For example:

```
taup pierce -mod prem -h 200 -ph S,P -deg 57.4
```

would give you pierce points for S, and P for a 200 kilometer deep source at a distance of 57.4 degrees.

While

```
taup pierce -turn -mod prem -h 200 -ph S,P -deg 57.4
```

would give you just the points that each ray turns from downgoing to upgoing.

Using `-rev` would give you all points that the ray changes direction and `-under` gives just the underside reflections.

Using the `-pierce` option

```
taup pierce -mod prem -h 200 -ph S -sta 12 34.2 -evt -28 122 --pierce 2591 --nodiscon
```

would give you just the points at which S crossed a depth of 2591 kilometers from an event at (28° S, 122° E) to a station at (12° N, 34.2° E). Because we specified the latitudes and longitudes, we also get the latitudes and longitudes of the pierce points, useful for making a map view of where the rays encounter the chosen depth. Here is the output, distance, depth, latitude and longitude, respectively.

```
> S at 1424.11 seconds at 93.70 degrees for a 200.0 km deep source in the prem mo
  31.56 2591.0 552.6 -17.87 89.41
  61.47 2591.0 822.0 -3.89 62.40
```

3.4 TauP_Path

TauP_Path uses a model like TauP_Time but generates the angular distances from the epicenter at which the specified rays pierce path that the phases travel. The output is in GMT (Wessel and Smith, 1995) “psxy” format, and is placed into the file “taup_path.gmt”. If you specify the “-gmt” flag then this is a complete script with the appropriate “psxy” command prepended, so if you have GMT installed, you can just:

```
taup path -mod iasp91 -h 550 -deg 74 -ph S,ScS,sS,sScS --gmt
sh taup_path.gmt
```

and you have a plot of the ray paths in “taup_path.pdf”. To avoid possible plotting errors for phases like Sdiff, the ray paths are interpolated to less than 1 degree increments.

The usage is:

```
piglet 5>taup path --help
Usage: taup path [arguments]
    or, for purists, java edu.sc.seis.TauP.TauP_Path [arguments]
```

Arguments are:

```
-ph phase list      -- comma separated phase list
-pf phasefile      -- file containing phases

-mod[el] modelname -- use velocity model "modelname" for calculations
                    Default is iasp91.

-h depth           -- source depth in km

--stadepth depth   -- receiver depth in km
```

Distance is given by:

```
-deg degrees       -- distance in degrees,
-km kilometers     -- distance in kilometers,
                    assumes radius of earth is 6371km,
```

or by giving the station and event latitude and longitude,
assumes a spherical earth,

```
-sta[tion] lat lon -- sets the station latitude and longitude
-evt          lat lon -- sets the event latitude and longitude
```

```
--first           -- only output the first arrival for each phase, no triplications
--withtime        -- include time for each path point
--gmt             -- outputs path as a complete GMT script.
--svg             -- outputs path as a complete SVG file.
--mapwidth        -- sets map width for GMT script.
```

```
-o [stdout|outfile] -- output is redirected to stdout or to the "outfile" file
--prop [propfile]  -- set configuration properties
--debug           -- enable debugging output
--verbose         -- enable verbose output
--version         -- print the version
--help           -- print this out, but you already know that!
```

3.5 TauP_Wavefront

TauP_Wavefront is similar to TauP_Path, but plots the wavefront at timesteps instead of the ray paths. It also uses a model like TauP.Time and generates depth versus angular distances from the epicenter for the phases, but done at time slices instead of depth slices. The output is in GMT ([Wessel and Smith, 1995](#)) "psxy" format, and is placed into the file "taup_wavefront.gmt". The columns are distance, depth, time and ray param, although only the first two are used by the GMT script. If you specify the "-gmt" flag then this is a complete script with the appropriate "psxy" command prepended, so if you have GMT installed, you can just:

```
taup wavefront -mod iasp91 -h 550 -ph S,ScS,sS,sScS --gmt
sh taup_wavefront.gmt
```

and you have a plot of the wavefronts in "taup_wavefront.pdf".

The usage is:

```

piglet 5>taup wavefront --help
Usage: taup wavefront [arguments]
  or, for purists, java edu.sc.seis.TauP.TauP_Wavefront [arguments]

```

Arguments are:

```

-ph phase list      -- comma separated phase list
-pf phasefile      -- file containing phases

-mod[el] modelname -- use velocity model "modelname" for calculations
                    Default is iasp91.

-h depth           -- source depth in km

--stadepth depth   -- receiver depth in km

```

Distance is given by:

```

-deg degrees       -- distance in degrees,
-km kilometers     -- distance in kilometers,
                    assumes radius of earth is 6371km,

```

or by giving the station and event latitude and longitude,
assumes a spherical earth,

```

-sta[tion] lat lon -- sets the station latitude and longitude
-evt      lat lon -- sets the event latitude and longitude

```

```

--rays num        -- number of raypaths/distances to sample.
--timestep num    -- steps in time (seconds) for output.
--timefiles       -- outputs each time into a separate .ps file within the gmt script.
--negdist         -- outputs negative distance as well so wavefronts are in both halves.

-o [stdout|outfile] -- output is redirected to stdout or to the "outfile" file
--prop [propfile]  -- set configuration properties
--debug           -- enable debugging output
--verbose         -- enable verbose output
--version         -- print the version
--help           -- print this out, but you already know that!

```

3.6 TauP_GUI

TauP_GUI is unlike the rest of the tools in that it doesn't have any functionality beyond the other tools. It is just a GUI that uses TauP_Time, TauP_Pierce and TauP_Path. This is a nice feature of the java language in that each of these applications exists simultaneously as a library. The GUI does not currently have full access to all the things that these three tools can do, and certainly has a few rough edges, but can be useful for browsing. Lastly, it currently does more work than it has to in that it always calculates times, pierce points and paths, even if only one is actually needed. So, it may be a bit pokey.

```
taup gui
```

3.7 TauP_Curve

TauP_Curve creates a GMT style xy formatted file of time versus distance. This can be used to create the familiar travel time curves, but for only the specified phases and depth. The curves are linearly interpolated between known sample points, and can thus be used to get a feel for the coarseness of sampling. For example, curves for s, S, ScS and Sdiff for a 500 kilometer deep event in PREM could be generated by:

```
taup curve -mod prem -h 500 -ph s,S,ScS,Sdiff --gmt
```

The `-gmt` option prepends a GMT `psxy` command to the output file, creating a runnable script instead of just a data file. The output is put in `taup_curve.gmt` by default, so to view the results:

```
sh taup_curve.gmt
```

and you have a plot of the wavefronts in “`taup_curve.pdf`”.

The usage is:

```
piglet 6>taup curve --help
```

```
Usage: taup_curve [arguments]
  or, for purists, java edu.sc.seis.TauP.TauP_Curve [arguments]
```

Arguments are:

```
-ph phase list      -- comma separated phase list
-pf phasefile      -- file containing phases

-mod[el] modelname -- use velocity model "modelname" for calculations
                   Default is iasp91.

-h depth           -- source depth in km

--gmt              -- outputs curves as a complete GMT script.
--svg              -- outputs curves as a SVG image.
--reddeg velocity  -- outputs curves with a reducing velocity (deg/sec).
--redkm velocity   -- outputs curves with a reducing velocity (km/sec).
--rel phasename    -- outputs relative travel time
--mapwidth width   -- sets map width for GMT script.

-o [stdout|outfile] -- output is redirected to stdout or to the "outfile" file
--prop [propfile]  -- set configuration properties
--debug            -- enable debugging output
--verbose          -- enable verbose output
--version          -- print the version
--help            -- print this out, but you already know that!
```

3.8 TauP_SetSac

TauP_SetSac uses the depth and distance information in SAC (Tull, 1989) file headers to put theoretical arrival times into the t_0 - t_9 header variables. The header variable for a phase can be specified with by a dash followed by a number, for instance $S-9$ puts the S arrival time in t_9 . If no header is specified then the time will be inserted in the first header variable not allocated to another phase, starting with 0. If there are no header variables not already allocated to a phase, then the additional phases will not be added to the header. Note that this does not refer to times that are already in the SAC file before TauP_SetSac is run. They will be overwritten. The ray parameter, in seconds per radian, is also inserted into the corresponding $user_0$ - $user_9$ header.

Note that triplicated phases are a problem as there is only one spot to put a time. For example, in iasp91 S has three arrivals at 20 degrees but only one can be put into the chosen header. TauP_SetSac assumes that the first arrival is the most important, and uses it. Additional header variables may be appended for the times of the multiples. For example, S-458 would put the first S arrival into header t_4 and the second into t_5 and the third into t_8 . If there are more arrivals than headers, the later arrivals are not added. If there are more headers than arrivals, then the header is not set.

Warning: TauP_SetSac assumes the EVDP header has depth in meters unless the `-evdpkm` flag is used, in which case kilometers are assumed. This may be a problem for users that improperly use kilometers for the depth units. Due to much abuse of the SAC depth header units, a warning message is printed if the depth appears to be in kilometers, i.e. it is < 1000 , and `-evdpkm` is not used. This can be safely ignored if the event really is less than 1000 meters deep. See the SAC manual (Tull, 1989) for confirmation.

The SAC files must have EVDP and the O marker set. Also, if GCARC or DIST is not set then TauP_SetSac can calculate a distance only if STLA, STLO, EVLA and EVLO are set.

The user should be very careful about previously set header variables. TauP_SetSac will overwrite any previously set t_{user} headers. A future feature may do more careful checking, but the current version makes no effort to verify that the header is undefined before writing.

If the given filename is a directory, TauP_SetSac will recursively look for files within that directory to process. Thus, a large directory structure of Sac files can be processed easily.

The usage is:

```

piglet 7>taup setsac --help
Usage: taup_setsac [arguments]
    or, for purists, java edu.sc.seis.TauP.TauP_SetSac [arguments]

Arguments are:
-ph phase list      -- comma separated phase list,
                    use phase-# to specify the sac header,
                    for example, ScS-8 puts ScS in t8
-pf phasefile      -- file containing phases

-mod[el] modelname -- use velocity model "modelname" for calculations
                    Default is iasp91.

--evdpkm           -- sac depth header is in km, default is meters

--prop [propfile]  -- set configuration properties
--debug           -- enable debugging output

```

```
--verbose          -- enable verbose output
--version          -- print the version
--help            -- print this out, but you already know that!
```

```
sacfilename [sacfilename ...]
```

```
Ex: taup_setsac --mod S_prem -ph S-8,ScS-9,PKP-a2 wmq.r wmq.t wmq.z
puts the first S arrival in T8 and ScS in T9, and the first PKP arrival into A
and the second into T2
```

3.9 TauP_Table

TauP_Table creates an ASCII table of arrival times for a range of depths and distances. Its main use is for generating travel time tables for earthquake location programs such as LOCSAT. The `--generic` flag generates a flat table with all arrivals at each depth and distance, one arrival per line. The `--csv` flag generates a comma separated value file, including a header while the `--json` flag will output the table data as JSON. The `--locsat` flag generates a LOCSAT style travel time table with only the first arrival of all the phases listed at each distance and depth. Thus, the program must be run several times in order to generate files for several phases. Also, all options write to standard out unless a file is given with the `-o` flag.

There is a default phase, distance and depth list, but this is easily customizable with the `--header` option. An example LOCSAT style file for use as a header can be generated with `taup table -locsat -o example.locsat`. The first three sections specify the phase list, distances and depths to use. After editing, a custom table can be created with `taup table -header example.locsat`.

Note that the `taup.table.locsat.maxdiff` property sets the cutoff beyond which `Pdiff` and `Sdiff` will not be output. This is to align the output with preexisting locsat style travel time files.

The usage is:

```
piglet 1>taup table --help
Usage: taup table [arguments]
    or, for purists, java edu.sc.seis.TauP.TauP_Table [arguments]
```

Arguments are:

```
-ph phase list      -- comma separated phase list
-pf phasefile       -- file containing phases

-mod[el] modelname -- use velocity model "modelname" for calculations
                    Default is iasp91.

-header filename    -- reads depth and distance spacing data
                    from a LOCSAT style file.
--csv               -- outputs a CSV ascii table
--generic           -- outputs a "generic" ascii table
--locsat           -- outputs a "locsat" style ascii table
--json              -- outputs a table as JSON

-o [stdout|outfile] -- output is redirected to stdout or to the "outfile" file
--prop [propfile]   -- set configuration properties
--debug            -- enable debugging output
```

```
--verbose          -- enable verbose output
--version          -- print the version
--help            -- print this out, but you already know that!
```

3.10 TauP_PhaseDescribe

TauP_PhaseDescribe outputs a textual description of the path the phase takes through the model.

For example:

```
taup phase -mod prem -h 200 -ph PKiKP
PKiKP:
  exists from      0.00 to   152.44 degrees.
  with ray parameter from  2.059 down to  0.000 sec/deg.
  travel times from 1170.37 to  966.27 sec.
P going down as a P in the mantle, layer 3 to 6, depths 200.0 to 2891.0, then transmit down
K going down as a P in the outer core, layer 7, depths 2891.0 to 5149.5, then reflect tops
K going up   as a P in the outer core, layer 7, depths 5149.5 to 2891.0, then transmit up
P going up   as a P in the crust/mantle, layer 6 to 0, depths 2891.0 to 0.0, then end
```

The usage is:

```
piglet 1> taup phase --help
Usage: arraylist [arguments]
  or, for purists, java java.util.ArrayList [arguments]

Arguments are:
-ph phase list      -- comma separated phase list
-pf phasefile      -- file containing phases

-mod[el] modelname -- use velocity model "modelname" for calculations
                    Default is iasp91.

-h depth           -- source depth in km

--stadepth depth   -- receiver depth in km

--dump            -- dump raw sample points

-o [stdout|outfile] -- output is redirected to stdout or to the "outfile" file
--prop [propfile]  -- set configuration properties
--debug           -- enable debugging output
--verbose         -- enable verbose output
--version         -- print the version
--help           -- print this out, but you already know that!
```

3.11 TauP_VelocityMerge

TauP_VelocityMerge overlays a partial velocity model over the given base velocity model. This makes it easy to overlay a new crust and upper mantle structure on an existing global model. For example if dumbcrust.nd contains:

```
0.0 3 2 4
5.0 3.1 2.1 4
21.0 3.2 2.2 4
mantle
21.0 8.1 4.4 3.3
30.0 8.1 4.4 3.3
```

then running

```
taup velmerge -mod prem --ndmerge dumbcrust.nd
```

would create a velocity model called prem_dumbcrust that contained:

```
0.0 3.0 2.0 4.0
5.0 3.1 2.1 4.0
21.0 3.2 2.2 4.0
mantle
21.0 8.1 4.4 3.3
30.0 8.1 4.4 3.3
30.0 8.107228461538462 4.488757435897436 3.3801497435897434
40.0 8.10119 4.48486 3.37906
60.0 8.08907 4.47715 3.37688
```

If the discontinuity at 30 km depth is not desired, the `-smbot` argument will create a smooth transition from the bottom of the new model to the first depth sample in the base model. Care should be taken with named discontinuities if they are different in the merged model by making sure there is enough depth in the merge to cover the named in both models. The merge model does not have to start at the surface, it can be just a range of depths.

The usage is:

```
piglet 1>taup velmerge --help
Usage: taup velmerge [arguments]
    or, for purists, java edu.sc.seis.TauP.TauP_VelocityMerge [arguments]
```

Arguments are:

```
-mod[el] modelname -- base velocity model "modelname" for calculations
                    Default is iasp91.

-nd modelfile      -- base "named discontinuities" velocity file
-tvel modelfile   -- base ".tvel" velocity file, ala ttimes

-ndmerge modelfile -- "named discontinuities" velocity file to merge
-tvelmerge modelfile -- ".tvel" velocity file to merge, ala ttimes
```

```

-smstop                -- smooth merge at top

-smbot                 -- smooth merge at bottom

-o [stdout|outfile]    -- output is redirected to stdout or to the "outfile" file
--prop [propfile]     -- set configuration properties
--debug               -- enable debugging output
--verbose             -- enable verbose output
--version             -- print the version
--help                -- print this out, but you already know that!

```

3.12 TauP_VelocityPlot

TauP_VelocityPlot outputs a gmt script that plots the given velocity model.

The usage is:

```

piglet 1>taup velplot --help
Usage: taup velplot [arguments]
    or, for purists, java edu.sc.seis.TauP.TauP_VelocityPlot [arguments]

```

Arguments are:

```

-mod[el] modelname -- use velocity model "modelname" for calculations
                    Default is iasp91.

-nd modelfile      -- "named discontinuities" velocity file
-tvel modelfile    -- ".tvel" velocity file, ala ttimes

-o [stdout|outfile] -- output is redirected to stdout or to the "outfile" file
--prop [propfile]  -- set configuration properties
--debug            -- enable debugging output
--verbose          -- enable verbose output
--version          -- print the version
--help            -- print this out, but you already know that!

```

3.13 TauP_SlownessPlot

TauP_SlownessPlot outputs a gmt script that plots the given slowness model.

The usage is:

```

piglet 1>taup slowplot --help
Usage: taup_slownessplot [arguments]
    or, for purists, java edu.sc.seis.TauP.TauP_SlownessPlot [arguments]

```

Arguments are:

```

    To specify the velocity model:
-nd modelfile      -- "named discontinuities" velocity file
-tvel modelfile   -- ".tvel" velocity file, ala ttimes

--debug           -- enable debugging output
--prop [propfile] -- set configuration properties
--verbose         -- enable verbose output
--version         -- print the version
--help           -- print this out, but you already know that!

```

3.14 TauP_Create

TauP_Create takes a ASCII velocity model file, samples the model and saves the tau model to a binary file. The output file holds all information about the model and need only be computed once. It is used by all of the other tools. There are several parameters controlling the density of sampling. Their values can be set with properties. See section 3.1, above.

Note that the use of TauP_Create is no longer required as the various tools can read velocity models directly and effectively call TauP_Create internally. However, if a model file will be used repeatedly, using a precomputed .taup file is more efficient.

The usage is:

```

piglet 8>taup create --help
Usage: taup_create [arguments]
    or, for purists, java edu.sc.seis.TauP.TauP_Create [arguments]

```

Arguments are:

```

    To specify the velocity model:
-nd modelfile      -- "named discontinuities" velocity file
-tvel modelfile   -- ".tvel" velocity file, ala ttimes

--debug           -- enable debugging output
--prop [propfile] -- set configuration properties
--verbose         -- enable verbose output
--version         -- print the version
--help           -- print this out, but you already know that!

```

modelfile is the ASCII text file holding the velocity model. The -nd format is preferred because the depths, and thus identities, of the major internal boundaries can be unambiguously determined, making phase name parsing easier. See section 7 for an example. For compatibility, we support the -tvel format currently used by the latest ttimes package, (Kennett, Engdahl, and Buland, 1995).

The output will be a file named after the name of the velocity file, followed by .taup. For example

```
taup create -nd prem.nd
```

produces prem.taup.

4 Phase naming in TauP

A major feature of the TauP Toolkit is the implementation of a phase name parser that allows the user to define essentially arbitrary phases through the earth. Thus, the TauP Toolkit is extremely flexible in this respect since it is not limited to a pre-defined set of phases. Phase names are not hard-coded into the software, rather the names are interpreted and the appropriate propagation path and resulting times are constructed at run time. Designing a phase-naming convention that is general enough to support arbitrary phases and easy to understand is an essential and somewhat challenging step. The rules that we have developed are described here. Most of phases resulting from these conventions should be familiar to seismologists, e.g. pP, PP, PcS, PKiKP, etc. However, the uniqueness required for parsing results in some new names for other familiar phases.

In traditional “whole-earth” seismology, there are 3 major interfaces: the free surface, the core-mantle boundary, and the inner-outer core boundary. Phases interacting with the core-mantle boundary and the inner core boundary are easy to describe because the symbol for the wave type changes at the boundary (i.e. the symbol P changes to K within the outer core even though the wave type is the same). Phase multiples for these interfaces and the free surface are also easy to describe because the symbols describe a unique path. The challenge begins with the description of interactions with interfaces within the crust and upper mantle. We have introduced two new symbols to existing nomenclature to provide unique descriptions of potential paths. Phase names are constructed from a sequence of symbols and numbers (with no spaces) that either describe the wave type, the interaction a wave makes with an interface, or the depth to an interface involved in an interaction.

1. Symbols that describe wave-type are:

P	compressional wave, upgoing or downgoing, in the crust or mantle
p	strictly upgoing P wave in the crust or mantle
S	shear wave, upgoing or downgoing, in the crust or mantle
s	strictly upgoing S wave in the crust or mantle
K	compressional wave in the outer core
k	strictly upgoing compressional wave in the outer core
I	compressional wave in the inner core
y	strictly upgoing compressional wave in the inner core
J	shear wave in the inner core
j	strictly upgoing shear wave in the inner core

2. Symbols that describe interactions with interfaces are:

m	interaction with the moho
g	appended to P or S to represent a ray turning in the crust
n	appended to P or S to represent a head wave along the moho
c	topside reflection off the core mantle boundary
i	topside reflection off the inner core outer core boundary
^	underside reflection, used primarily for crustal and mantle interfaces
v	topside reflection, used primarily for crustal and mantle interfaces
V	critical topside reflection, used primarily for crustal and mantle interfaces
diff	appended to P or S to represent a diffracted wave along the core mantle boundary, or to K for a diffracted wave along the inner-outer core boundary
kmps	appended to a velocity to represent a horizontal phase velocity (see 11 below)
ed	appended to P, S, K, I or J to represent a exclusively downgoing path, for a receiver below the source (see 3 below)

3. The characters p, s, k, y and j **always** represent up-going legs. An example is the source to surface leg of the phase pP from a source at depth. P and S can be turning waves, but always indicate downgoing waves leaving the source when they are the first symbol in a phase name. Thus, to get near-source, direct P-wave arrival times, you need to specify two phases p and P or use the “times compatibility phases” described

below. However, P may represent a upgoing leg in certain cases. For instance, P_cP is allowed since the direction of the phase is unambiguously determined by the symbol c , but would be named P_{cP} by a purist using our nomenclature. The phase k is similar to p but is an upgoing compressional wave in the outer core, while y and j are upgoing compressional and shear waves in the inner core. The name y is used as the lower case of the I phase is already used to indicate reflection from the inner-outer core boundary.

With the ability to have sources at depth, there is a need to specify the difference between a wave that is exclusively downgoing to the receiver from one that turns and is upgoing at the receiver. The suffix ed can be appended to indicate exclusively downgoing. So for a source at 10 km depth and a receiver at 20 km depth at 0 degree distance the turning ray P does not have an arrival but P_{ed} does.

4. Numbers, except velocities for k_{mps} phases (see 11 below), represent depths at which interactions take place. For example, P_{410s} represents a P-to-S conversion at a discontinuity at 410km depth. Since the S-leg is given by a lower-case symbol and no reflection indicator is included, this represents a P-wave converting to an S-wave when it hits the interface from below. The numbers given need not be the actual depth, the closest depth corresponding to a discontinuity in the model will be used. For example, if the time for P_{410s} is requested in a model where the discontinuity was really located at 406.7 kilometers depth, the time returned would actually be for $P_{406.7s}$. The code “taup time” would note that this had been done via the “Purist Name”. Obviously, care should be taken to ensure that there are no other discontinuities closer than the one of interest, but this approach allows generic interface names like “410” and “660” to be used without knowing the exact depth in a given model.
5. If a number appears between two phase legs, e.g. S_{410P} , it represents a transmitted phase conversion, not a reflection. Thus, S_{410P} would be a transmitted conversion from S to P at 410km depth. Whether the conversion occurs on the down-going side or up-going side is determined by the upper or lower case of the following leg. For instance, the phase S_{410P} propagates down as an S, converts at the 410 to a P, continues down, turns as a P-wave, and propagates back across the 410 and to the surface. S_{410p} on the other hand, propagates down as a S through the 410, turns as an S, hits the 410 from the bottom, converts to a p and then goes up to the surface. In these cases, the case of the phase symbol (P vs. p) is critical because the direction of propagation (upgoing or downgoing) is not unambiguously defined elsewhere in the phase name. The importance is clear when you consider a source depth below 410 compared to above 410. For a source depth greater than 410 km, S_{410P} technically cannot exist while S_{410p} maintains the same path (a receiver side conversion) as it does for a source depth above the 410.

The first letter can be lower case to indicate a conversion from an up-going ray, e.g. p_{410S} is a depth phase from a source at greater than 410 kilometers depth that phase converts at the 410 discontinuity. It is strictly upgoing over its entire path, and hence could also be labeled p_{410s} . p_{410S} is often used to mean a reflection in the literature, but there are too many possible interactions for the phase parser to allow this. If the underside reflection is desired, use the $p^{\wedge}410S$ notation from rule 7.

6. Due to the two previous rules, P_{410P} and S_{410S} are over specified, but still legal. They are almost equivalent to P and S , respectively, but restrict the path to phases transmitted through (turning below) the 410. This notation is useful to limit arrivals to just those that turn deeper than a discontinuity (thus avoiding travel time curve triplications), even though they have no real interaction with it.
7. The characters \wedge , \vee and ∇ are new symbols introduced here to represent bottom-side and top-side reflections, respectively. They are followed by a number to represent the approximate depth of the reflection or a letter for standard discontinuities, m , c or i . The lower-case \vee represents a generic reflection while ∇ is a critical reflection. Note however, that ∇ is critical in the sense of without phase conversion. In other words, $P_{\nabla mp}$ is critical for ray parameters where a P wave cannot propagate into the mantle, regardless of whether or not S can propagate. A critical reflection phase using ∇ is always a subset of the non-critical reflection using \vee . Reflections from discontinuities besides the core-mantle boundary, c ; or inner-core outer-core boundary, i , must use the \wedge and \vee notation. For instance, in the TauP convention, $p^{\wedge}410S$ is used to describe a near-source underside reflection.

Underside reflections, except at the surface (PP , SS , etc.), core-mantle boundary ($PKKP$, $SKKKS$, etc.), or outer-core-inner-core boundary ($PKIIKP$, $SKJJKS$, $SKIIKS$, etc.), must be specified with the $\hat{}$ notation. For example, $\hat{P}410P$ and \hat{P}_mP would both be underside reflections from the 410km discontinuity and the Moho, respectively. Because of the difficulty of creating interfaces where critical underside reflections can occur in earth-like models, we have not added this capability.

The phase P_mP , the traditional name for a top-side reflection from the Moho discontinuity, must change names under our new convention. The new name is $P_{vm}P$ or PV_{mp} while P_mP just describes a P-wave that turns beneath the Moho. The reason the Moho must be handled differently from the core-mantle boundary is that traditional nomenclature did not introduce a phase symbol change at the Moho. Thus, while P_{cP} makes sense since a P-wave in the core would be labeled K , P_mP could have several meanings. The m symbol just allows the user to describe phases interaction with the Moho without knowing its exact depth. In all other respects, the $\hat{}$ - v nomenclature is maintained.

8. Starting in version 2.7, $\hat{}$ and v are now allowed for for all discontinuities in the model, including the crust, mantle and core. However, because “ p is to P ” is not the same as “ i is to I ”, a naming convention was created to use y as an exclusively upgoing leg in the inner core. For example in a model with a discontinuity at 5500 km depth in the inner core, the phases $PKIv5500IKP$ and $PKIv5500ykp$ are the same. Note that because standard models do not have discontinuities in the core, these phases have not received the same level of testing.
9. Starting in version 2.7, \circ and \bigcirc represent forward and back scattering, if the model is constructed with a scatterer (depth and distance). Forward scattering is in the sense that the phase continues around the earth in the same direction, while backscattering would reverse direction. Note that for some phases that go the long way around the earth, the sense of scattering may not match the positive angular direction.
10. Currently there is no support for PKP_{ab} , PKP_{bc} , or PKP_{df} phase names. They lead to increased algorithmic complexity that at this point seems unwarranted, and TauP uses phase names to describe paths, but PKP_{ab} and PKP_{bc} differentiate between two arrivals from the same path, PKP . Currently, in regions where triplications develop, the triplicated phase will have multiple arrivals at a given distance. So, PKP_{ab} and PKP_{bc} are both labeled just PKP while PKP_{df} is called $PKIKP$.
11. The symbol k_{mps} is used to get the travel time for a specific horizontal phase velocity. For example, $2k_{mps}$ represents a horizontal phase velocity of 2 kilometers per second. While the calculations for these are trivial, it is convenient to have them available to estimate surface wave travel times or to define windows of interest for given paths.
12. As a convenience, a *ttimes* phase name compatibility mode is available. So ttp gives you the phase list corresponding to P in *ttimes*. Similarly there are tts , $ttp+$, $tts+$, $ttbasic$ and $ttall$.

5 Creating and Saving Velocity Models

5.1 Velocity Model Files

There are currently two variations of velocity model files that can be read. Both are piecewise linear between given depth points. Support for cubic spline velocity models would be useful and is planned for a future release.

The first format is that used by the most recent times codes (Kennett, Engdahl, and Buland, 1995), `.tvel`. This format has two comment lines, followed by lines composed of depth, V_p , V_s and density, all separated by whitespace. TauP ignores the first two lines of this format and reads the remaining lines.

The second format is based on the format used by Xgbm, (Davis and Henson, 1993a; Davis and Henson, 1993b). It is referred to here as the `.nd` format for "named discontinuities." Its biggest advantage is that it can specify the location of the major boundaries and this makes it the preferred format. The file consists of two types of lines, those that specify velocity at a depth, and those that specify the name of a discontinuity.

The first type of line has between 3 and 6 numbers on a line separated by whitespace. They are, in order, depth in kilometers to the sample point, P velocity in kilometers per second, S velocity in kilometers per second, density in grams per cubic centimeter, Q_p attenuation for compressional waves and Q_s attenuation for shear waves. Only depth, V_p and V_s are required. The remaining parameters, while not needed for travel time calculations, are included to allow the model to be used for other purposes in the future. The model is assumed to be linear between given depths and repeated depths are used to represent discontinuities.

The second type of line within the `.nd` format specifies one of the three major internal boundaries, *mantle* for the crust-mantle boundary, *outer-core* for the outer core-mantle boundary, or *inner-core* for the inner core-outer core boundary. These labels are placed on a line by themselves between the two lines representing the sample points above and below the depth of the discontinuity. These help to determine where a particular phase propagates. For instance, in a model that has many crustal and upper mantle layers, from which discontinuity does the phase P_{vmP} reflect? Explicit labeling eliminates potential ambiguity.

One further enhancement to these model file formats is the support for comments embedded within the model files. As in shell scripting, everything after a `#` on a line is ignored. In addition, C style `/* ... */` and C++ style `// ...` comments are recognized.

A very simple *named discontinuities* model file might look like this:

```
/* below is a simple named discontinuities model. */
0.0  5.0  3.0  2.7
20   5.0  3.0  2.7
20   6.5  3.7  2.9
33   6.5  3.7  2.9
mantle      # the word "mantle" designates that this is the moho
33   7.8  4.4  3.3
410  8.9  4.7  3.5
410  9.1  4.9  3.7
670  10.2 5.5  4.0
670  10.7 5.9  4.4
2891 13.7 7.2  5.6
outer-core  # "outer-core" designates that this is the core mantle boundary
2891 8.0  0.0  9.9
5149.5 10.3 0.0 12.2
inner-core  # "inner-core" makes this the inner-outer core boundary
5149.5 11  3.5 12.7
```

6371 11.3 3.7 13

In many cases it is better and easier to make use of `taup velmerge` to create a new model by making changes to an existing global model, especially when for example the user only cares about crust and upper mantle structure and is happy with `prem` for the lower mantle and core. Hand editing velocity model files often results in hard to catch errors.

5.2 Using Saved Tau Models

There are three ways of finding a previously generated model file. First, as a standard model as part of the distribution. Second, a list of directories and jar files to be searched can be specified with the `taup.model.path` property. Lastly, the path to the actual model file may be specified. TauP searches each of these places in order until it finds a model that matches the name.

1. Standard Model.

TauP first checks to see if the model name is associated with a standard model. Several standard models are included within the distributed jar file. They include `iasp91` (Kennett and Engdahl, 1991), `prem` (Dziewonski and Anderson, 1984), `ak135` (Kennett, Engdahl, and Buland, 1995), `jb` (Jeffreys and Bullen, 1940), `1066a` (Gilbert and Dziewonski, 1975), `1066b` (Gilbert and Dziewonski, 1975), `pwdk` (Weber and Davis, 1990), `sp6` (Morelli and Dziewonski, 1993) and `herrin` (Herrin, 1968). Lastly, we have included `qdt`, which is a coarsely sampled version of `iasp91` (Kennett and Engdahl, 1991). It is smaller, and thus loads quicker, but has significantly reduced accuracy. We will consider adding other models to the distribution if they are of wide interest. They are included within the distribution jar file but `taup` can locate them with just the model name.

2. Within the `taup.model.path` property.

Users can create custom models, and place the stored models in a convenient location. If the `taup.model.path` property includes those directories or jar files, then they can be located. The search is done in the order of `taup.model.path` until a model matching the model name is found. While `taup.model.path` is a Java property, the shell scripts provided translate the environment variable `TAUPPATH` into this property. The user generally need not be aware of this fact except when the tools are invoked without using the provided shell scripts. A more desirable method is to set the `taup.model.path` in a properties file. See section 3.1 for more details.

The `taup.model.path` property is constructed in the manner of standard Java `CLASSPATH` which is itself based loosely on the manner of the UNIX `PATH`. The only real differences between `CLASSPATH` and `PATH` are that a jar file may be placed directly in the path and the path separator character is machine dependent, UNIX is `:` but other systems may vary.

The `taup.model.path` allows you to have directories containing saved model files as well as jar files of models. For instance, in a UNIX system using the `c` shell, you could set your `TAUPPATH` to be, (all one line):

```
setenv TAUPPATH /home/xxx/MyModels.jar:/home/xxx/ModelDir:  
/usr/local/lib/localModels.jar
```

or you could place a line in the `.taup` file in your home directory that accomplished the same thing, again all one line:

```
taup.model.path=/home/xxx/MyModels.jar:/home/xxx/ModelDir:  
/usr/local/lib/localModels.jar
```

If you place models in a jar, TauP assumes that they are placed in a directory called `Models` before they are jarred. For example, you might use `taup_create` to create several `taup` models in the `Models` directory and then create a jar file.

```
jar -cf MyModels.jar Models
```

Including a `“.”` for the current working directory with the `taup.model.path` is not necessary since we always check there, see [3](#) below, but it may be used to change the search order.

3. The last place TauP looks is for a model file specified on the command line. So, if you generate `newModel.taup` and want to get some times, you can just say: `taup_time -mod newModel.taup` or even just `taup_time -mod newModel` as TauP can add the `taup` suffix if necessary. A relative or absolute pathname may precede the model, e.g. `taup_time -mod ../OtherDir/newModel.taup`. New in version 2.0 is the ability of the tools to load a velocity model directly and handle the create functionality internally, so in addition to `.taup` files, the `.nd` and `.tvel` model files can be loaded if there is not a `.taup` file found. Note that there is extra work involved in processing the velocity file, and so frequently used models should still be converted using `TauP_Create` to avoid reprocessing them each time the tool starts.

6 Programming Interface

In addition to the command line interface, there are three ways to access the toolkit from within other programs. The most straightforward is through Java. Using Groovy or Jacl provides a very nice way to write scripts that use the tools without repeatedly starting up the Java virtual machine and reloading models. Lastly, there is a C language interface, but it is a bit less friendly. Descriptions of all three, with example programs are below.

6.1 Java

The TauP package should be easily used by future Java programs. An example is given illustrating the basics of using the package to generate travel times. You may wish to refer to the javadocs, either included in the distribution or available at <https://javadoc.io/doc/edu.sc.seis/TauP>.

First, instantiate a `TauP.Time` object. This provides methods for generating and using travel times and should be sufficient for most purposes. However, in order to actually generate anything useful, the `TauP.Time` object needs a `TauModel`. It can be loaded within the constructor for `TauP.Time` as a `TauModel` or with the model name. It can be changed later using either the `TauP.Time.setTauModel(TauModel)` method of `TauP.Time`, or by passing the modelname to `TauP.Time.loadTauModel(String)`. The later is likely easier, and has the advantage of searching for the model in the distribution jar file, the locations in the `taup.model.path` property, and the current directory.

```
TauP.Time timeTool = new TauP.Time("mymodel");
```

In addition to the `TauModel`, a collection of phases is also needed. Again, there are several ways of accomplishing this. `parsePhaseList(String)` is likely the easiest method. A `String` is passed with the phase names separated by commas and the phases are extracted and appended. Phases can also be input more directly with `setPhaseNames(String[])`, which sets the phases to be those in the array, and `appendPhaseName(String)` which appends a phase to the list. Note that these methods do not do any checking to assure the names are valid phases, this is done at a later stage. Of additional interest are `clearPhaseNames()` which deletes all current phase names, and `getPhaseNames()` which returns an array of `Strings` with the phase names.

```
timeTool.parsePhaseList("P,Pdiff,S,Sdiff,PKP,SKS");
```

The next step is to correct the `TauModel` for the source depth. The `TauModel` is created with a surface source, but can be corrected for a source at depth, given in kilometers, with the `setSourceDepth(double)` method. The actual depth correction is time consuming, and so is delayed until the `calculate` method is called. In addition, if a correction was actually needed, it calls `recalcPhases()` which verifies that the times and distances for the phases in the phase list are compatible with the current model and depth. `recalcPhases()` is also called by `calculate()` in case changes were made to the list of phase names.

```
timeTool.setSourceDepth(100.0);
```

It remains only to calculate arrivals for a particular distance using the `calculate(double)` method, which takes an angular distance in degrees. The arrivals are stored as `Arrival` objects, which contain `time`, `dist`, `rayParam`, `sourceDepth`, and `name` fields. The `Arrivals` can be accessed through either the `getArrival(int)` method which returns the `i`th arrival, or the `getArrivals()` method which returns an array of `Arrivals`. Of additional interest is the `getNumArrivals()` method that returns the number of arrivals.

```
timeTool.calculate(40);
Arrival[] arrivals = timeTool.getArrivals();
for (int i=0; i<arrivals.length; i++) {
    System.out.println(arrivals[i].getName+" arrives at "+
        (arrivals[i].getDist*180.0/Math.PI)+" degrees after "+
```

```

        arrivals[i].getTime+" seconds.");
    }

```

It is important to realize that all internal angular distances are stored as radians, hence the conversion, and times in seconds. This also means that the ray parameters are stored as seconds per radian.

6.2 Scripting

One of the problems with Java based tools is that there is overhead associated with starting a Java program due to the fact that the virtual machine must first be started. While with normal interactive computing this is not such a large problem, it can become very wasteful when repeated calling a tool from within a script. Significant time savings can be had if the tool and its associated virtual machine can be kept alive for the duration of the script.

There are several scripting languages available that allow access to compiled java code, including Groovy, <http://www.groovy-lang.org/>, and Kotlin, <https://kotlinlang.org/> along with ports of existing scripting languages to the JVM like Jython, <https://www.jython.org/> and JACL, <https://wiki.tcl-lang.org/page/Jacl>. These may be used to create more complicated calculations than are possible with the command line tools, or to do repeated tasks much more efficiently.

One point to keep in mind when scripting TauP is that the depth correction is much more expensive than the distance calculation. So looping over all stations for each earthquake is much faster than looping over all earthquakes for each station.

6.2.1 Groovy

Groovy is a nice scripting language that interfaces very well with java. Even nicer, with the '@Grab' functionality, it can download needed jar files automatically, so you do not even have to install TauP in order to run this script.

Here we calculate travel times for a few phases at 60 degrees distance for a 100 km deep source. For each arrival, we print the phase name and arrival time, then print the pierce points that show the very coarse path through the model.

```

@Grab('edu.sc.seis:TauP:2.7.0')
import edu.sc.seis.TauP.TauP_Time
import edu.sc.seis.TauP.Arrival
import edu.sc.seis.TauP.TimeDist

def taup_time = new TauP_Time("prem")

taup_time.clearPhaseNames()
taup_time.parsePhaseList("P,PcP,S,ScS")
taup_time.setSourceDepth(100)
taup_time.calculate(60)
for(Arrival a: taup_time.getArrivals()) {
    println a.name+" "+a.time
    for(TimeDist piercePoint : a.getPierce()) {
        println " "+piercePoint.distDeg+" "+piercePoint.time
    }
}

```

6.2.2 Jacl

Note: Jacl might still be a useful scripting choice, but it does not appear to have been updated in many years. We include this section for reference, but you may wish to choose another language.

Jacl, a Java implementation of the popular Tool Command Language or Tcl, makes writing scripts that use the TauP Toolkit easy, and allows one instance of both the virtual machine as well as the tool to remain active for the whole script. You may download jacl from <http://www.scriptics.com/java>.

Jacl allows a script to create Java objects, call any public method of those objects and manipulate their attributes. Thus, creating a script to do many similar calculations or a custom application that makes these tools usable in the way you want is as easy as writing a tcl script. We present a brief walkthrough of a Jacl script that calculates pierce points for numerous station event pairs.

The first three lines of the script should start up jacl. The second line is a bit of trickery, it hides the third line from jacl while allowing sh to see it. Jacl takes the backslash to be a line continuation marker, and therefore accepts the third line as part of the comment started on the second line. This just makes it easier to start up jacl without having to know the exact path in advance.

```
#!/bin/sh
# \
exec jacl $0 $*
```

Next, we will set up latitudes and longitudes for our stations and events. This was modified from a script that read from a CSS database, but in order to keep the script self contained, we have hardwired it here.

```
set slat(0) 35
set slon(0) -5
set elat(0) 125
set elon(0) 5
set edepth(0) 100
set elat(1) -10
set elon(1) 110
set edepth(1) 100
set elat(2) 40
set elon(2) 140
set edepth(2) 200
set elat(3) 65
set elon(3) -5
set edepth(3) 10
```

Now we start up the pierce tool with the prem model and add the phases we are interested in. We will only do P and S in PREM for simplicity.

```
set taup [java::new [list edu.sc.seis.TauP.TauP_Pierce String] "prem"]
$taup clearPhaseNames
$taup {parsePhaseList java.lang.String} "P,S"
```

Here we get, and then loop over, all the discontinuities in the model in order to find the one closest to 400 kilometers depth.

```
set disconArray [$taup getDisconDepths]
```

```

set maxDiff 99999999
set bestDepth 0
for {set i 0} {$i < [$disconArray length]} {incr i} {
  set depth [$disconArray get $i]
  if { [expr abs($depth - 400)] < $maxDiff} {
    set maxDiff [expr abs($depth - 400)]
    set bestDepth $depth
  }
}

```

Loop over all events and stations and output the pierce point at the 400 kilometer discontinuity. We use the `getLastPiercePoint(depth)` method as we want the receiver side pierce point. If we wanted the source side point we could have used the `getFirstPiercePoint(depth)` method.

```

for {set eventIndex 0} {$eventIndex < [array size elat]} {incr eventIndex} {
  $taup depthCorrect $edepth($eventIndex)
  for {set staIndex 0} {$staIndex < [array size slat]} {incr staIndex} {
    set gcarc [java::call edu.sc.seis.TauP.SphericalCoords distance \
      $elat($eventIndex) $elon($eventIndex) \
      $slat($staIndex) $slon($staIndex)]
    set az [java::call edu.sc.seis.TauP.SphericalCoords azimuth \
      $elat($eventIndex) $elon($eventIndex) \
      $slat($staIndex) $slon($staIndex)]
    $taup calculate $gcarc
    set numArrivals [$taup getNumArrivals]

    if {$numArrivals == 0} {
      puts "No arrivals for event $eventIndex"
    }
    for {set k 0} {$k < $numArrivals} {incr k} {
      set OneArrival [$taup getArrival $k]
      set name [ $OneArrival getName]

      if [ catch \
        {set OnePierce [$OneArrival getLastPiercePoint $bestDepth]} ] {
        puts "$name doesn't pierce $bestDepth for event $eventIndex"
        continue
      }

      set dist [ $OnePierce getDist]
      set dist [expr $dist * (180./3.14159)]
      set plat [java::call edu.sc.seis.TauP.SphericalCoords latFor \
        $elat($eventIndex) $elon($eventIndex) $dist $az ]
      set plon [java::call edu.sc.seis.TauP.SphericalCoords lonFor \
        $elat($eventIndex) $elon($eventIndex) $dist $az ]
      puts [format "(%-7.3f, %-7.3f) $name from event number $eventIndex" \
        $plat $plon ]
    }
  }
}

```

And here is the output:

```

piglet 56>./pierce.jacl
No arrivals for event 0
(-7.218 , 36.679 ) P from event number 1
(-7.214 , 36.676 ) S from event number 1
(-2.185 , 35.266 ) P from event number 2
(-2.205 , 35.264 ) S from event number 2
(-3.262 , 34.492 ) P from event number 3
(-3.142 , 34.457 ) S from event number 3

```

This script, along with another simple travel time script, is included in the distribution in the jacl subdirectory.

6.3 C

Here be monsters!

A C language interface to the TauP package is provided. A shared library libtaup.so, provides access to the core functionality for generating travel times. An example program using these interface routines is also provided, gettimes.c.

A word of warning, nothing in Java is as fraught with peril as JNI. This part of the TauP Toolkit is the hardest to get working. It is recommended that you be fluent in both C and Java and have a high pain tolerance before attempting to integrate TauP into a C program. In addition, the native code provided has not been maintained and comes with no expectation that it will compile, much less work. You have been warned!

The native interface is distributed as C source code that you must compile on your local machine. A makefile is provided to generate a shared library and an example code to call the library. The makefile was created for use under Solaris, but doesn't do anything particularly special, and should be easily modifiable for other operating systems.

Of course, the system must be able to find this library, as well as the Java libraries. Under Solaris, this can be accomplished with the `LD_LIBRARY_PATH` environment variable. Other systems may vary. The `CLASSPATH` environment variable must also contain the `taup.jar` file as well as the default java jar files. Note that under Java1.2 the command line tools may work fine while the C interface has problems. This is due to the java executable finding the standard files without the `CLASSPATH`. The C interface bypasses the executable, and so does not benefit from this. Properly setting the `CLASSPATH` is thus even more important for calling Java from C.

The current C interface only provides method calls for the most basic operations for getting travel times. If less common methods need to be called then a quick look at the source code in the native directory should be sufficient to create new hooks into those methods.

The state of the travel time calculator is preserved from call to call within a `TauPStruct` structure. This contains references to the java virtual machine, each of the method calls and the current model. This structure is always the first argument to all of the method calls. While I believe this is the least complicated style of interaction, it is not particularly memory or processor efficient for uses involving more than one travel time calculator active simultaneously. Primarily this is due to having more than one java virtual machine running at the same time. Still, it is a good example of how C can interact with Java.

The currently implemented method calls are:

TauPInit initializes the java virtual machine and properly fills in the `TauPStruct` passed as the first argument. The second argument is the name of the model to be used. The method signature is
`int TauPInit(TauPStruct *tauptr, char *modelName);`

TauPSetDepth sets the source depth within the model. A initialized `TauPStruct` is passed as the first argument,

with the source depth passed as the second. With the exception of creating a new model, this is the most CPU intensive operation. The method signature is
`int TauPSetDepth(TauPStruct taup, double depth) ;`

TauPClearPhases clears any previously added phases. This should be followed by a call to `TauPAppendPhases`, below, to add new phases. An initialized `TauPStruct` is passed as the first argument. The method signature is
`int TauPClearPhases(TauPStruct taup) ;`

TauPAppendPhases appends new phases for calculation. An initialized `TauPStruct` is passed as the first argument and the phase names are passed as a comma or space separated string in the second argument. All of the phase names that can be used in the interactive code can be used here. Also, duplicates are checked for and eliminated before being added. The method signature is
`int TauPAppendPhases(TauPStruct taup, char *phaseString) ;`

TauPCalculate calculates all arrivals for all of the current phases for the distance specified in the second argument. An initialized `TauPStruct` is passed as the first argument. The method signature is
`int TauPCalculate(TauPStruct taup, double degrees) ;`

TauPGetNumArrivals returns the number of arrivals found with the last call to `TauPCalculate`, above. A negative number indicates an error. An initialized `TauPStruct` is passed as the first argument. The method signature is
`int TauPGetNumArrivals(TauPStruct taup) ;`

TauPGetArrival returns the *i*th arrival found with the last call to `TauPCalculate`, above. The arrival is returned as a `Jobect`, which is mainly useful if it will be used as an argument for another java method call. `NULL` is returned if an error occurs. An initialized `TauPStruct` is passed as the first argument. The method signature is
`Jobect TauPGetArrival(TauPStruct taup, int arrivalNum) ;`

TauPGetArrivalName returns the name of the *i*th arrival found with the last call to `TauPCalculate`, above, as a character pointer. An initialized `TauPStruct` is passed as the first argument and the arrival number is passed as the second. `NULL` is returned if there is an error. The method signature is
`char * TauPGetArrivalName(TauPStruct taup, int arrivalNum) ;`

TauPGetArrivalPuristName returns the purist's version of the name of the *i*th arrival found with the last call to `TauPCalculate`, above, as a character pointer. The purist's name replaces depths with the true depth of interfaces in the phase name, for example `Pv410P` might really be `Pv400P`. An initialized `TauPStruct` is passed as the first argument and the arrival number is passed as the second. `NULL` is returned if there is an error. The method signature is
`char * TauPGetArrivalPuristName(TauPStruct taup, int arrivalNum) ;`

TauPGetArrivalTime returns the travel time of the *i*th arrival found with the last call to `TauPCalculate`, above. An initialized `TauPStruct` is passed as the first argument and the arrival number is passed as the second. A negative number is returned if there is an error. The method signature is
`double TauPGetArrivalTime(TauPStruct taup, int arrivalNum) ;`

TauPGetArrivalDist returns the travel distance of the *i*th arrival found with the last call to `TauPCalculate`, above. An initialized `TauPStruct` is passed as the first argument and the arrival number is passed as the second. A negative number is returned if there is an error. The method signature is
`double TauPGetArrivalDist(TauPStruct taup, int arrivalNum) ;`

TauPGetArrivalRayParam returns the ray parameter of the *i*th arrival found with the last call to `TauPCalculate`, above. An initialized `TauPStruct` is passed as the first argument and the arrival number is passed as the second. A negative number is returned if there is an error. The method signature is
`double TauPGetArrivalRayParam(TauPStruct taup, int arrivalNum) ;`

TauPGetArrivalSourceDepth returns the source depth of the *i*th arrival found with the last call to `TauPCalculate`, above. An initialized `TauPStruct` is passed as the first argument and the arrival number is passed as the second. A negative number is returned if there is an error. The method signature is
`double TauPGetArrivalSourceDepth(TauPStruct taup, int arrivalNum) ;`

TauPDestroy destroys the java virtual machine and frees the used memory. An initialized `TauPStruct` is passed as the first argument. A nonzero error is returned if there is an error. The method signature is
`int TauPDestroy(TauPStruct taup) ;`

7 Examples

Here is a walk through of a use of the tools on a UNIX system.

7.1 Velocity Model Files

First, we want to create a model. There are several models contained within the TauP distribution, but for completeness we will create a new one from scratch.

A very simple model file might look like this:

```
0.0      5.0  3.0  2.7
20       5.0  3.0  2.7
20       6.5  3.7  2.9
33       6.5  3.7  2.9
mantle
33       7.8  4.4  3.3
410      8.9  4.7  3.5
410      9.1  4.9  3.7
670     10.2  5.5  4.0
670     10.7  5.9  4.4
1000    11.5  6.4  4.6
2000    12.9  6.9  5.1
2891    13.7  7.2  5.6
outer-core
2891     8.0  0.0  9.9
3500     9.0  0.0 10.8
5149.5  10.3  0.0 12.2
inner-core
5149.5  11    3.5 12.7
5500    11.1  3.6 12.9
6371    11.3  3.7 13
```

Note that we have chosen the “named discontinuities” format so that we could specify the location of the major boundaries. The file consists of two types of lines, those that specify velocity at a depth, and those that specify the name of a discontinuity. See section 5.1 for more details.

7.2 Creating the Model

If we put this into a file called “simpleMod.nd” then we can run `taup create` to create a model sampling. We use the `-verbose` option to get some additional output. In particular, it outputs the radius to the surface for this model. Having an incorrect radius, which could happen for instance if the last line of the model file was lost, will generate incorrect times for phases that otherwise appear fine. This can be a difficult error to track down after the fact because there is nothing wrong with the model, it is just not what was intended. As they say, “garbage in, garbage out.”

```
piglet 10>taup create -nd simpleMod.nd --verbose
TauP_Create starting...
```

```

filename = ./simpleMod.nd
Done reading velocity model.
Radius of model simpleMod is 6371.0
Parameters are:
taup.create.minDeltaP = 0.1 sec / radian
taup.create.maxDeltaP = 11.0 sec / radian
taup.create.maxDepthInterval = 115.0 kilometers
taup.create.maxRangeInterval = 2.5 degrees
taup.create.maxInterpError = 0.05 seconds
taup.create.allowInnerCoreS = true
Slow model 514 P layers, 581 S layers
Done Saving ./simpleMod.taup
Done!
Done!
piglet 11>ls
simpleMod.nd      simpleMod.taup

```

The file `simpleMod.taup` contains all of the information about the model. This process needs to be done only once for each velocity model. The times appearing in the output are in milliseconds, and do not reflect the startup time for Java.

7.3 Travel Times

Now that we have the model sampled, computing travel times is easy. We will use `taup` time to get the travel times for some familiar phases, P, S, PcP, ScS, SKS, sS, and SS in our simple model for a 143.2 kilometer deep source and at a distance of 75 degrees. We use the “-mod” command line flag to specify the model, and then do the rest after it starts.

First `taup` time reads a standard Java Properties file, “.taup”, that it finds in my home directory. See section 3.1 for more details. If there are phases you are interested in frequently, or model you use often, or source depth, then you can put them in this file as your defaults. Then we enter a depth for the source, 143.2 kilometers, using the `h` option. By default, the model is for a surface source.

Some phase names have been read in from the file, but we want to specify our own phase list, so we use the ‘`c`’ option to clear the phases and are prompted to enter the new phases. Enter them separated by commas or spaces. After that we just need to enter the distance, 75 degrees. The arrivals are printed as distance, depth, phase name, time and then ray parameter. The last two entries represent a “purists” view of the distance and phase name. For instance, PKKP travels the long way around the earth, and so the true distance traveled is not the event to station distance. The purist’s view of the name is to show the difference between the true depths of discontinuities and the depth specified in the phase name. For instance, Pv400P in our simple model is really a reflection off of the discontinuity at 410 kilometers depth. The purist’s name reflects this and is preceded by an asterisk to make the difference easier to notice. The distance is repeated to make it easier to parse the output from within scripts.

```

piglet 4>taup time --mod simpleMod
Enter:
h for new depth
r to recalculate
p to append phases,
c to clear phases
l to list phases
s for new station lat lon

```

e for new event lat lon
 a for new azimuth
 b for new back azimuth
 t for takeoff angle
 m for new model or
 q to quit.

```
Enter Distance or Option [hrpclseabmqt]: h
Enter Depth: 143.2
Enter Distance or Option [hrpclseabmqt]: c
Enter phases (ie P,p,PcP,S): P,S,PcP,ScS,SKS,sS,SS,PKKP
Enter Distance or Option [hrpclseabmqt]: 75
```

Model: simpleMod

Distance (deg)	Depth (km)	Phase Name	Travel Time (s)	Ray Param p (s/deg)	Takeoff (deg)	Incident (deg)	Purist Distance	Purist Name
75.00	143.2	P	686.34	5.722	25.31	14.91	75.00	= P
75.00	143.2	PcP	700.51	4.312	18.79	11.18	75.00	= PcP
75.00	143.2	S	1263.17	11.042	27.12	17.33	75.00	= S
75.00	143.2	SKS	1293.35	7.283	17.50	11.33	75.00	= SKS
75.00	143.2	ScS	1298.74	8.135	19.63	12.68	75.00	= ScS
75.00	143.2	sS	1326.74	11.153	152.58	17.51	75.00	= sS
75.00	143.2	SS	1571.75	14.643	37.20	23.27	75.00	= SS

```
Enter Distance or Option [hrpclseabmqt]: q
```

We could also have done this same example by just using the command line options.

```
piglet 5>taup time -mod simpleMod -h 143.2 -deg 75 -ph P,S,PcP,ScS,SKS,sS,SS,PKKP
```

Model: simpleMod

Distance (deg)	Depth (km)	Phase Name	Travel Time (s)	Ray Param p (s/deg)	Takeoff (deg)	Incident (deg)	Purist Distance	Purist Name
75.00	143.2	P	686.34	5.722	25.31	14.91	75.00	= P
75.00	143.2	PcP	700.51	4.312	18.79	11.18	75.00	= PcP
75.00	143.2	S	1263.17	11.042	27.12	17.33	75.00	= S
75.00	143.2	SKS	1293.35	7.283	17.50	11.33	75.00	= SKS
75.00	143.2	ScS	1298.74	8.135	19.63	12.68	75.00	= ScS
75.00	143.2	sS	1326.74	11.153	152.58	17.51	75.00	= sS
75.00	143.2	SS	1571.75	14.643	37.20	23.27	75.00	= SS

7.4 Pierce Points

Now, where are the turning points for these rays? We can run `taup pierce` with the “-turn” flag and find out. Lets specify the parameters on the command line. The output is distance in degrees followed by depth in kilometers. Note that SS has two turning points.

```
piglet 7>taup pierce -mod simpleMod -h 143.2 -deg 75 -ph P,S,PcP,ScS,SKS,sS,SS,PKKP -turn
```

```

> P at 686.34 seconds at 75.00 degrees for a 143.2 km deep source in the simpleMod
    37.23 2110.8 332.4
> PcP at 700.51 seconds at 75.00 degrees for a 143.2 km deep source in the simpleMod
    37.30 2891.0 339.9
> S at 1263.17 seconds at 75.00 degrees for a 143.2 km deep source in the simpleMod
    37.20 2008.5 612.3
> SKS at 1293.35 seconds at 75.00 degrees for a 143.2 km deep source in the simpleMod
    37.31 2975.3 628.5
> ScS at 1298.74 seconds at 75.00 degrees for a 143.2 km deep source in the simpleMod
    37.29 2891.0 631.0
> sS at 1326.74 seconds at 75.00 degrees for a 143.2 km deep source in the simpleMod
    37.81 1971.2 682.7
> SS at 1571.75 seconds at 75.00 degrees for a 143.2 km deep source in the simpleMod
    18.09 1003.2 361.4
    56.03 1003.2 1168.3

```

7.5 Path

Perhaps now we should make a plot of the paths. Lets use only command line options and send the output to the file “simpleModPaths.gmt” instead of the default “taup_path.gmt”.

```

piglet 8>taup path -mod simpleMod -h 143.2 -deg 75 \
? -ph P,S,PcP,ScS,SKS,sS,SS,PKKP \
? -o simpleModPaths.gmt -gmt
piglet 9>ls
simpleMod.taup      simpleMod.nd      simpleModPaths.gmt
piglet 10>bash simpleModPaths.gmt
piglet 11>ls
simpleMod.taup      simpleModPaths.ps
simpleMod.nd        simpleModPaths.gmt

```

Now we have a Postscript file, simpleModPaths.ps, that we can look at or print. Notice that we used the `-gmt` flag so that the output is a complete GMT script. If you don't use `-gmt`, then the output is just the XY points, which might be later used by another script. Of course, this only works if you have GMT installed.

7.6 Travel Time Curves

If we want to see the travel time curves for these phases, we can do that using `taup curve`. It works very similarly to `taup_path` except that we don't need to specify a distance.

```

piglet 12>taup curve -mod simpleMod -h 143.2 -ph P,S,PcP,ScS,SKS,sS,SS,PKKP \
? -o simpleModCurves.gmt -gmt
piglet 13>ls
simpleModCurves.gmt  simpleMod.nd      simpleModPaths.gmt
simpleMod.taup       simpleModPaths.ps
piglet 14>sh simpleModCurves.gmt
piglet 15>ls
simpleMod.nd          simpleModCurves.gmt  simpleModPaths.gmt
simpleMod.taup        simpleModCurves.ps   simpleModPaths.ps

```

Again we have a Postscript file to view. Both of these commands generate scripts that are ok for a quick look, but you will almost certainly want to modify them for any important use.

A Installing

The installation for TauP under UNIX is quite simple. And with Java's platform independence, the package should be usable on a Mac or Windows machine.

A.0.1 Max OSX Install

For Mac OSX, we recommend Homebrew, <https://brew.sh/>. Installation is easy with:

```
brew tap crotwell/crotwell
brew install taup
taup help
```

A.0.2 Snap Install

For linux, Snap, <https://snapcraft.io/taup>, provides an easy alternative to a manual install.

```
sudo snap install taup
taup help
```

A.0.3 Manual Install

1. Install a Java 1.8 or better virtual machine. If your system already has Java 1.8 or better installed then you can skip to the next step. You can test this with "java -version". If it isn't there or the version is less than 1.8 you need to get and install Java. Most operating systems come with a version of Java, and so this should not be an issue. If you do need to download Java, point your browser to <https://openjdk.java.net/> and download and install the Java SE Development Kit for Macintosh, Linux or Windows. TauP may run under earlier version of Java, but they are no longer supported.
2. Download TauP.X.X.X.tar.gz or TauP.X.X.X.zip. Make sure to get the most recent version, replacing the X's in the file name. They can be found at <http://www.seis.sc.edu/TauP>
3. Unpack the distribution.

```
gunzip TauP.X.X.X.tar.gz
tar -xvf TauP.X.X.X.tar
or
jar -xvf TauP.X.X.X.zip
or unzip TauP.X.X.X.zip
```

This will create a directory called TauP-X.X.X. Inside will be the files and directories listed in chapter 2, Distribution.
4. Put this directory someplace. It really doesn't matter where, although a central place might make administration easier, /usr/local or /usr/local/share are good choices. If you don't have superuser privileges then your home directory is fine.

Previous versions of TauP recommended installing taup.jar as a *standard extension* by placing the jar file into the jre/lib/ext subdirectory of your java installation. We no longer believe this is a good practice, and if you have done this in the past you will need to remove the old version in order to prevent a conflict.

5. Set the location of the TauP directory in your TAUP_HOME environment variable. This should be done in your .cshrc or .login. For instance, if you put Taup-2.6.0 in /usr/local/share, then you could set the TAUP_HOME to be:

```
setenv TAUP_HOME /usr/local/share/Taup-2.6.0
```

for csh/tcsh or for bash

```
export TAUP_HOME=/usr/local/share/Taup-2.6.0
```

Please make sure that an old version of taup.jar is not on your CLASSPATH as this will cause a conflict.

6. Put the bin directory of the distribution directory in your PATH environment variable,

```
${TAUP_HOME}/bin
```

for instance. These wrapper scripts are not essential, but they cut down on typing. They are in the bin directory of the distribution and are simple UNIX sh scripts and bat files for windows.

7. Lastly, you may need to either source your .login and .cshrc files or execute the rehash command to make the shell reevaluate the contents of your PATH.

That's it. If you have problems or encounter bugs, please mail them to me. Please try to be as specific as possible. I am also interested in ideas for additional features that might make this a more useful program. Of course, I can make no promises, but I would be glad to hear about them.

I can be reached via email at crotwell@seis.sc.edu.

B Troubleshooting

There are a few idiosyncrocies about the codes and Java in general that you may run into.

1. Out of memory errors. Java's default maximum memory for most uses should be fine, but some very complicated models using a large number of phases may exceed this limit. A simple fix is to change the maximum memory to be a larger amount. The `-Xmx` command line argument to the `java` command does this. So, to set the maximum amount of memory to 128 megabytes you could say `java -Xmx128m edu.sc.seis.TauP.TauP_Path`. For convenience you may wish to make this change more permanent by adding it to the scripts, i.e. `taup_time`, etc. Also note that the `m` at the end specifies megabytes, if you omit it, then the value is 128 bytes, which is probably not what you want.
2. Garbled jar files. Care should be taken with the jar files when transferring them from one operating system to another. Certain file transfer utilities make an attempt to *fix* text files by changing `RETURN LINEFEED` sequences to just `LINEFEED` or just `RETURN` or vice versa. This is useful for real text files, but dangerous for jar files. I have noticed this when transferring files between UNIX and Macintosh, and it likely can happen between any two operating systems with differing end of line identifiers. Using binary mode for ftp transactions is likely wise.
3. Trouble with bat files. I don't use windows and so I do not know if the bat files are really useful or not. If you find a better method, I would be happy to include it.

References

- Buland, R. and C. H. Chapman (1983). The Computation of Seismic Travel Times, *Bull. Seism. Soc. Am.* **73**(5), 1271–1302.
- Crotwell, H. P., T. J. Owens, and J. Ritsema (1998). The TauP ToolKit: Flexible Seismic Travel-Time and Raypath Utilities, *Seismological Research Letters*. In Preparation.
- Davis, J. P. and I. H. Henson (1993a). Development of an X-Windows tool to compute Gaussian beam synthetic seismograms. Technical Report TGAL-93-03, Phillip Laboratory, Hancoff AFB, MA.
- Davis, J. P. and I. H. Henson (1993b). *User's Guide to Xgbm: An X-Windows System to compute Gaussian beam synthetic seismograms* (1.1 ed.). Alexandria, VA: Teledyne Geotech Alexandria Laboratories.
- Dziewonski, A. M. and D. L. Anderson (1984). Structure, elastic and rheological properties and density of the earth's interior, gravity and pressure. In K. Fuch and H. Soffel (Eds.), *Landoldt-Börnstein, Group V*, Volume 2a, pp. 84–96. Berlin: Springer.
- Gilbert, F. and A. M. Dziewonski (1975). An application of normal mode theory to the retrieval of structural parameters and source mechanisms from seismic spectra, *Philosophical Transactions of the Royal Society, London A* **278**, 187–269.
- Herrin, E. (1968). 1968 seismological tables for P phases, *Bull. Seism. Soc. Am.* **58**(4), 1193–1241.
- Jeffreys, H. and K. E. Bullen (1940). *Seismological Tables*. London: British Association for the Advancement of Science, Burlington House.
- Kennett, B. L. N. and E. R. Engdahl (1991). Traveltimes for global earthquake location and phase identification, *Geophysical Journal International* **105**, 429–465.
- Kennett, B. L. N., E. R. Engdahl, and R. Buland (1995). Constraints on seismic velocities in the Earth from traveltimes, *Geophysical Journal International* **122**, 108–124.
- Morelli, A. and A. M. Dziewonski (1993). Body wave traveltimes and a spherically symmetric P- and S-wave velocity model, *Geophysics Journal International* **112**(2), 178–194.
- Tull, J. E. (1989). *SAC - Seismic Analysis Code: User's Manual* (Revision 2 ed.). Livermore, CA: Lawrence Livermore National Laboratory.
- Weber, M. and J. P. Davis (1990). Evidence of a laterally variable lower mantle structure from P- and S-waves, *Geophysics Journal International* **102**(1), 231–255.
- Wessel, P. and W. H. F. Smith (1995). New Version of the Generic Mapping Tools released, *Eos* **76**, 329.